

# The Intersection of IoT and CPS

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# Credit

- Edward Griffor – Framework, Mathematical models
- Marty Burns – Framework, Pivotal Points of Interoperability
- David Wollman – Framework, Physical and Logical Interactions

# Outline

- Definitions
- Illustrative Scenarios
- Mathematical Models
- Framework

# CPS: Examples of Current Definitions

Cyber-physical systems (CPS) are engineered systems that are built from, and depend upon, the seamless integration of computational algorithms and physical components.

[US National Science Foundation](#)

Cyber-physical systems integrate sensing, computation, control and networking into physical objects and infrastructure, connecting them to the Internet and to each other.

[CPS Virtual Organization](#)

Cyber-physical systems (CPS) are smart systems that include engineered interacting networks of physical and computational components.

[CPS Public Working Group \(NIST\)](#)

In such technical systems, which are often called cyber-physical systems (CPS), real-time computing elements and physical systems interact tightly. ...The merging of IoT and CPS into closed-loop, real-time IoT-enabled cyber-physical systems is seen as an important future challenge.

[PICASSO Project Opportunity Report](#)

# IoT: Examples of Current Definitions

An infrastructure of interconnected objects, people, systems and information resources together with intelligent services to allow them to process information of the physical and the virtual world and react.

[ISO/IEC JTC1, 2015](#)

The Internet of Things (IoT) has been defined in Recommendation ITU-T Y.2060 as a global infrastructure for the information society, enabling advanced services by interconnecting (physical and virtual) things based on existing and evolving interoperable information and communication technologies.

[ITU-TY.400/Y.2060](#)

IoT refers to any systems of interconnected people, physical objects, and IT platforms, as well as any technology to better build, operate, and manage the physical world via pervasive data collection, smart networking, predictive analytics, and deep optimization.

[IEEE-SA IoT Ecosystem Study 2015](#)

# Relationship Between CPS and IoT: Examples

In most academic and project activities, the difference between “Internet of Things” and “Cyber-Physical Systems (CPS)” is not made clear and it is difficult to find a source that draws a clear-cut distinction ... Yet, identified objects in an IoT system can still be networked together so as to control a certain scenario in a coordinated way, in which case an IoT system can be considered to grow to the level of a CPS.

[IEEE \(2015\) Towards a Definition of the Internet of Things](#)

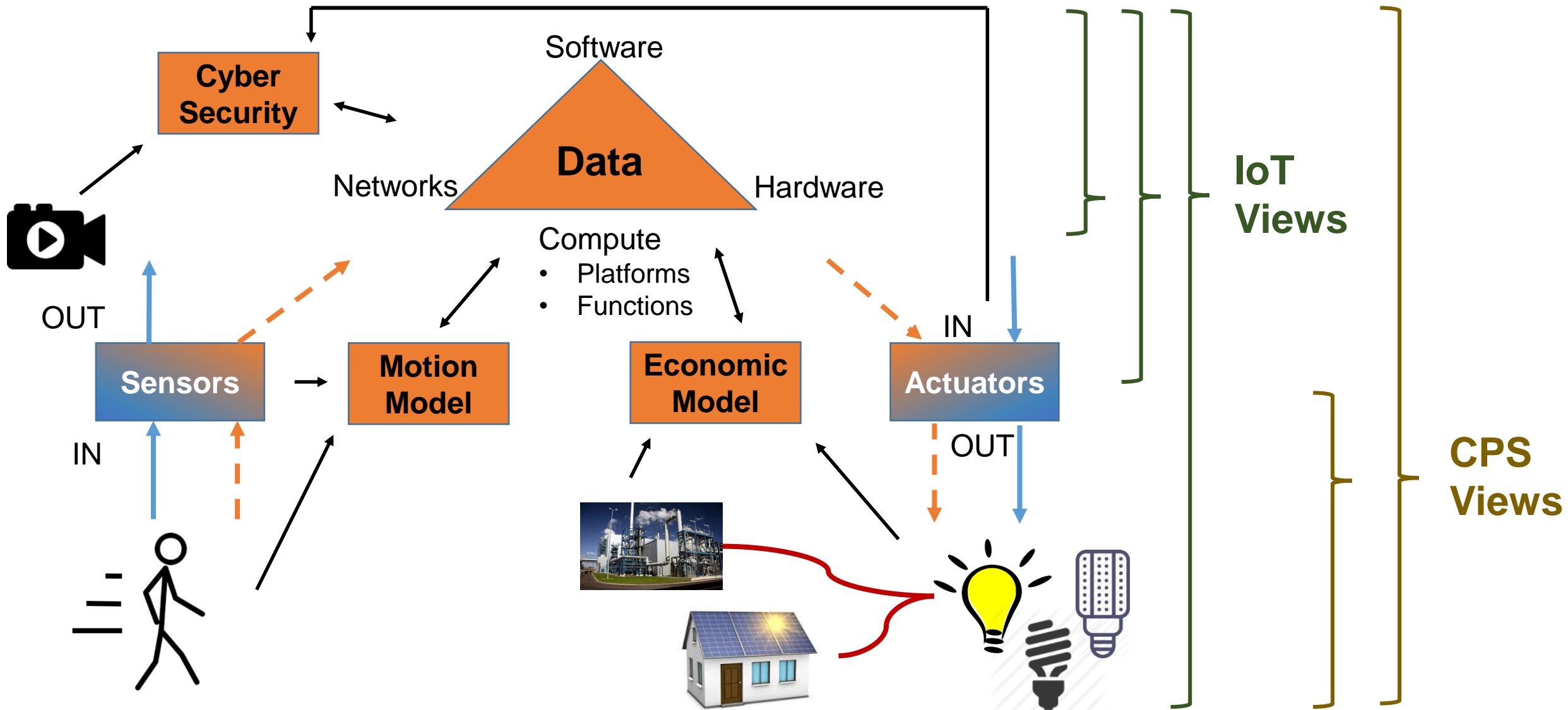
According to the PICASSO definition, the IoT is seen as an enabling technology for CPS or CPSoS (System of Systems) ... The merging of IoT and CPS into closed-loop, real-time IoT-enabled cyber-physical systems is seen as an important future challenge.

[PICASSO Project Opportunity Report](#)

# Outline

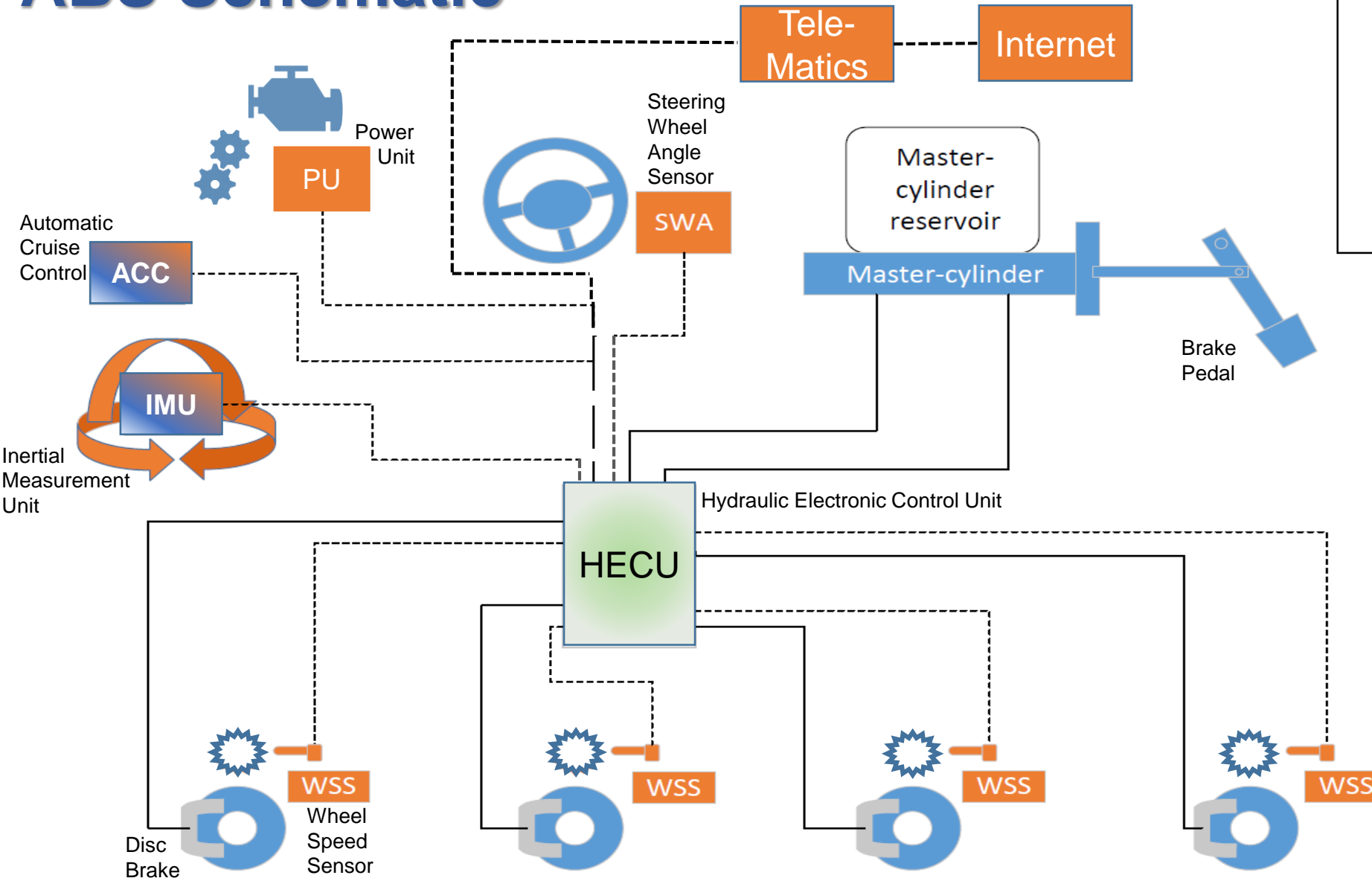
- Definitions
- **Illustrative Scenarios**
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# CPS vs IoT From the Examples: Home Energy Management System





# ABS Schematic

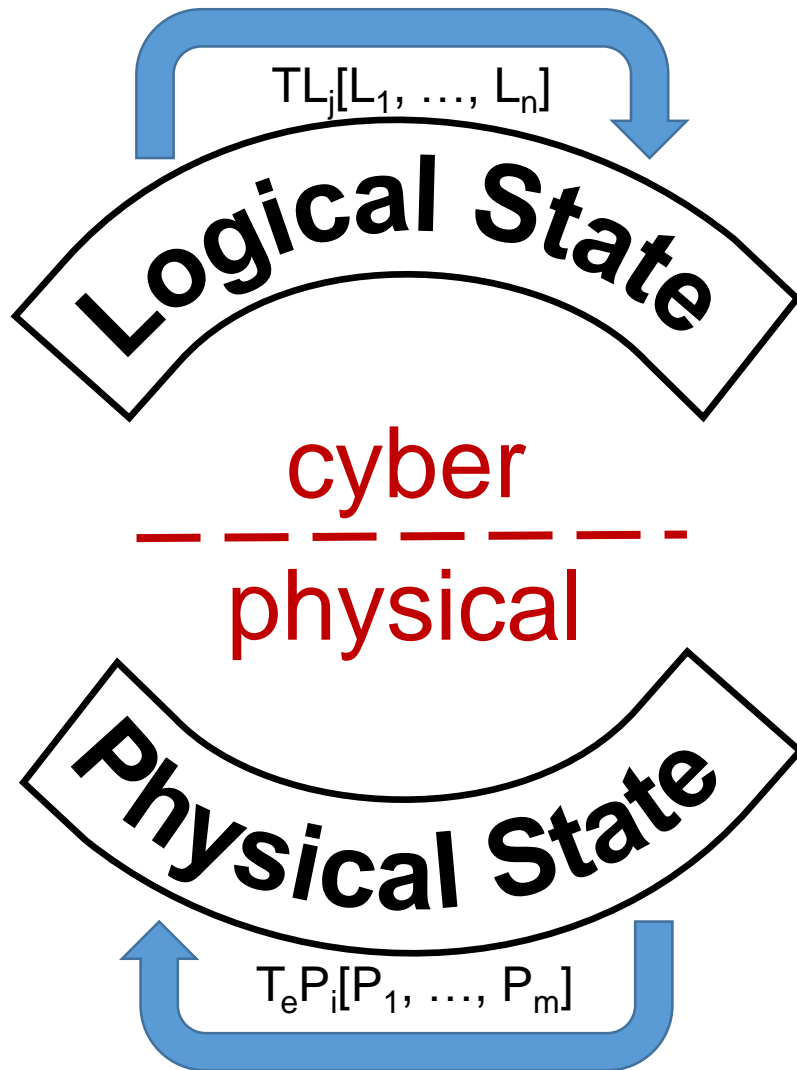


Derived from original figure by Ricardo  
www.ricardo.com

# Outline

- Definitions
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- **Mathematical Models**
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# Unified CPS Mathematical Model



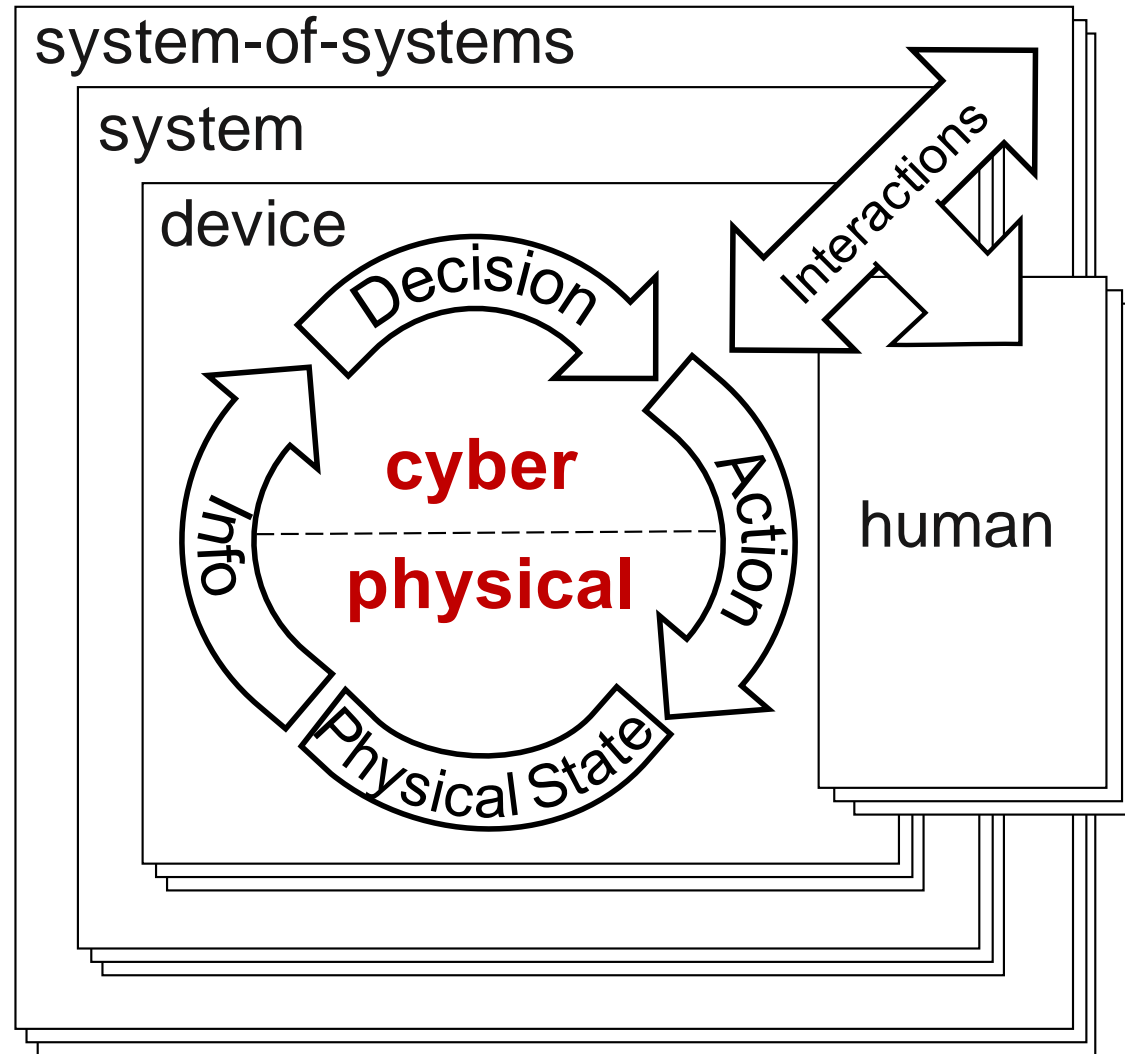
- *Logical State of a CPS* is a vector of *logical state parameters*  $\langle L_1, \dots, L_n \rangle$
- The Logical State is acted upon by algorithms  $TL_1, \dots, TL_k$  (each can be viewed as an operator on  $\langle L_1, \dots, L_n \rangle$ , resulting in  $\langle L'_1, \dots, L'_n \rangle$ ;
- *Physical state of a CPS* is a vector of *physical state parameters*  $\langle P_1, \dots, P_m \rangle$ ;
- a physical state vector is a solution to an algebraic system of differential equations (each equation describing a *waveform* for a choice of free variables)
- The Physical State is acted upon by energy exchange processes, represented by algebraic systems of ODEs,  $T_{e1}, \dots, T_{ek}$

# Representing CPS: Symmetric Monoidal Categories

- For purposes here **systems will be viewed as processes and interactions between them** (*process algebra* in the sense of Milnor for example)
- We distinguish two sorts of interactions between processes:
  - **Logical interactions** (exchanges of information)
  - **Physical interactions** (exchanges of energy)
- Math model of physical interactions is **algebraic systems of ODEs**
- Math model of logical interactions are **formalizations of agent-based models** such as *complex adaptive systems* (J. Holland)
- We choose symmetric monoidal categories (SMC) as an example of a **model of systems in category theory**

# Relation between CPS and IoT

**Cyber-Physical Systems (CPS)** comprise interacting digital, analog, physical, and human components engineered for function through integrated physics and logic.

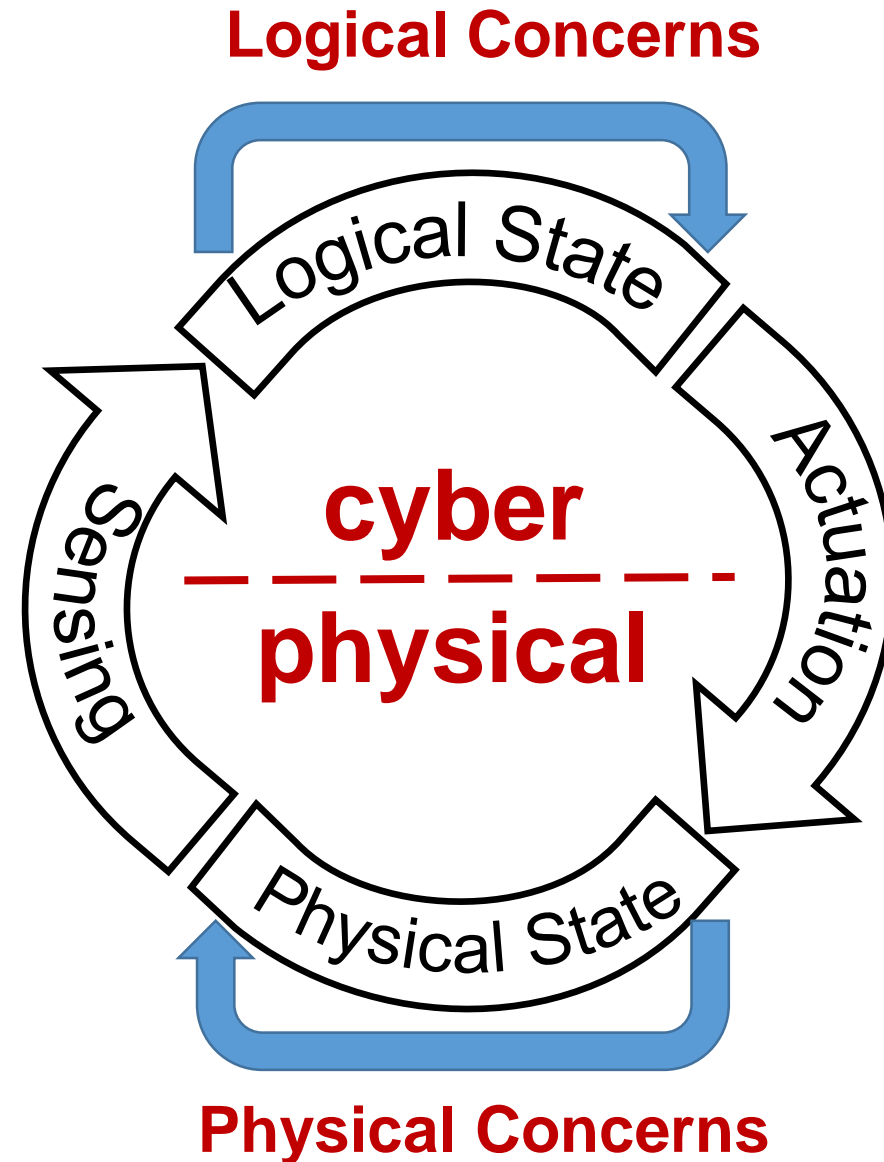


- Examples include a smart grid, a self-driving car, a smart manufacturing plant, an intelligent transportation system, a smart city, and Internet of Things (IoT) instances connecting new devices for new data streams and new applications.
- Common notions of IoT have emphasized networked sensors providing data streams to applications.
- CPS concepts complete these IoT notions, providing the means for conceptualizing, realizing and assuring all aspects of the composed systems of which sensors and data streams are components.

*The Framework for Cyber-Physical Systems* was released by the NIST CPSPWG on May 26, 2016

# CPS Mathematical Models

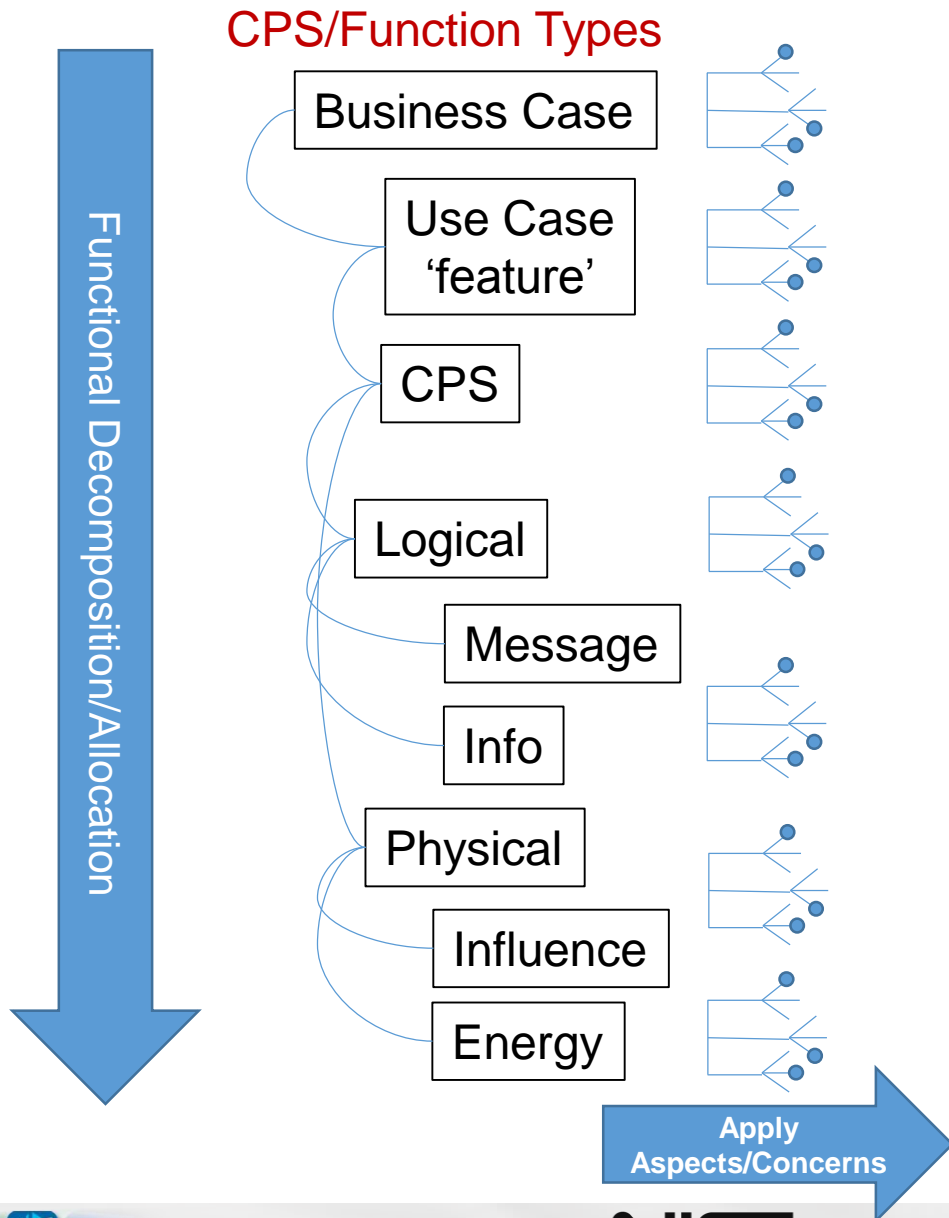
- Connecting logical and physical forms of concerns using interactions between the logical and physical states of a CPS
- Math of these interactions can provide a unified cyber-physical science.
- Sensing and Actuation 'connect' properties of the logical and physical elements of the CPS design



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# Analyzing and Developing CPS: Decomposition



## Safety "Properties" of a decomposed Function: AEB

AEB – vehicle provides automated collision safety function

AEB – vehicle provides/maintains safe stopping

AEB –braking function reacts as required

AEB – messaging function receives distance to obstacles and speed from propulsion function

AEB – distance and speed info is understood by braking function

AEB – stopping algorithm provided safe stopping

AEB – friction function provides appropriate friction





# CPS Framework

Domains

Manufacturing

Transportation

Energy

Healthcare

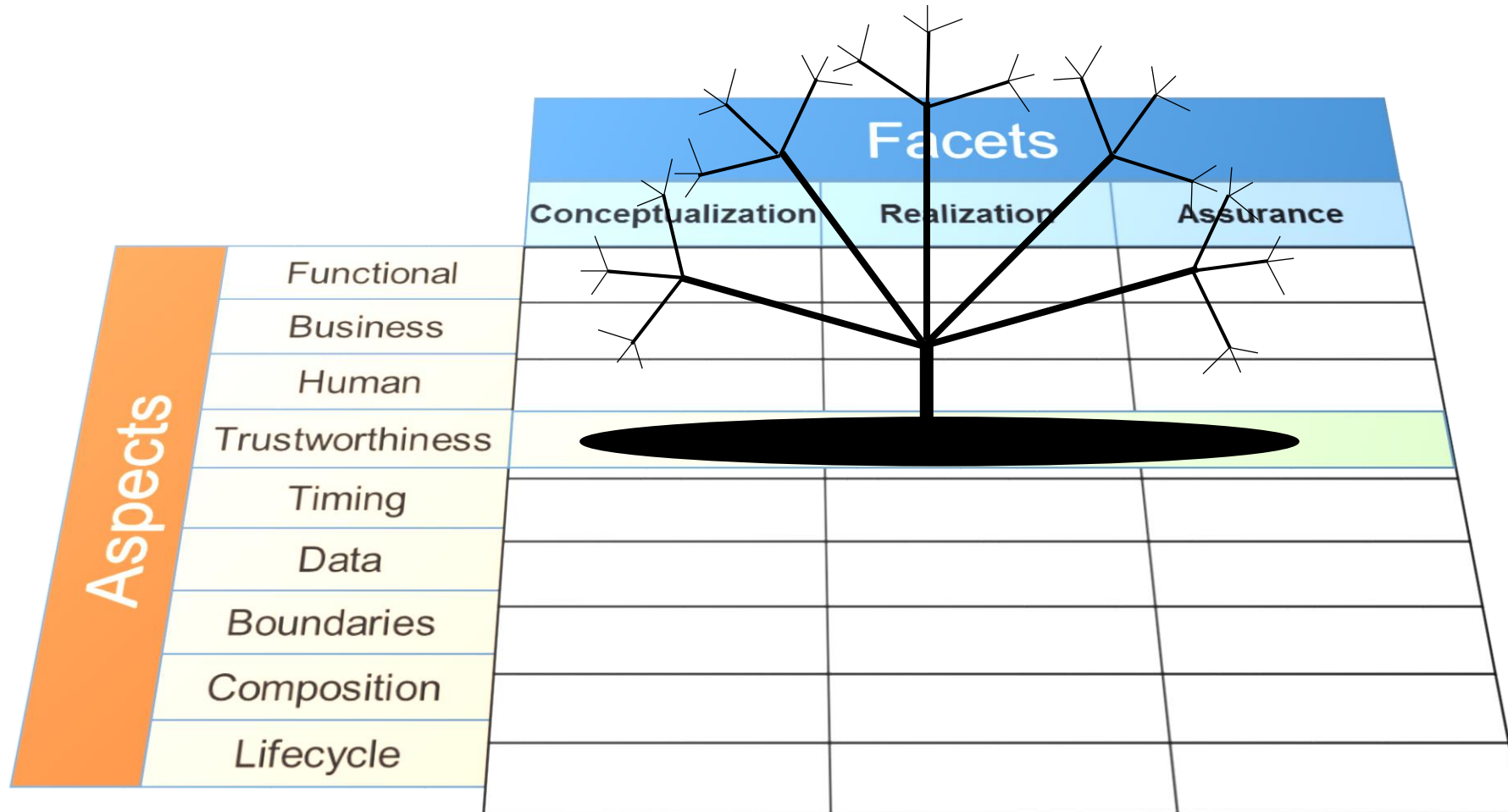
... Domain



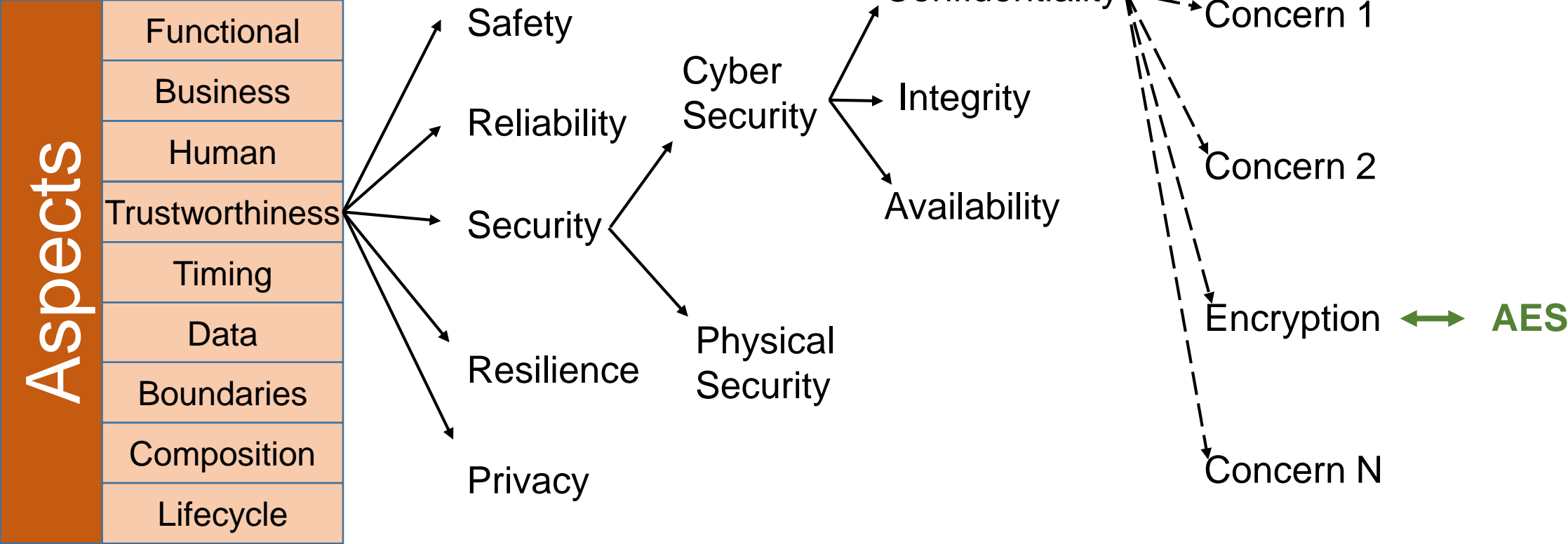
		Facets		
		Conceptualization	Realization	Assurance
Aspects	Functional			
	Business			
	Human			
	Trustworthiness			
	Timing			
	Data			
	Boundaries			
	Composition			
	Lifecycle			

*The Framework for Cyber-Physical Systems* was released by the NIST CPSPWG on May 26, 2016, see [pages.nist.gov/cpspwg](http://pages.nist.gov/cpspwg)

# CPS Concern Tree



# CPS Concern Tree



A privacy protected message exchange might consist of the set of properties:  
 {Trustworthiness.Security.Cybersecurity.Confidentiality.Encryption.AES,  
 Trustworthiness.Privacy.Predictability.Controls.Authorization.OAuth}

# Concern-Driven Analysis of a Standard

Common Concern:  
Trustworthiness.Security.Cybersecurity.confidentiality

Clause in document:  
TS-0002 clause 6.4

Solution: Access Control  
and Authorization,  
TS-0003 clause 7

Technology level (Device, System, System of Systems)					
Technology scope description (text)					
Concern	Aspect/Concern	Discussion of Concern	Discussion Reference(s)	Solution	Solution Reference(s)
Functional	Functional	in general	n/a		
Trustworthiness	Trustworthiness				
privacy	privacy	authorization, privacy and all the security requirements are defined	TS-0002 clause 6.4	Use proper access control settings under control of the data subject (individual whose privacy is exposed by the data)	TS-0003 Clause 7
reliability	reliability	in terms of message delivery, yes	tbd	CMDH(connection management and delivery handling) CSF and its resource types	TS-0001 clause 6.2.2
resilience	resilience	in terms of message delivery, yes	tbd	CMDH(connection management and delivery handling) CSF and its resource types	TS-0001 clause 6.2.2
safety	safety	Every deployment requires a risk and vulnerability assessment	TR-0008	Perform proper risk and vulnerability assessment and mitigate unacceptable risks	Any Risk assessment methodology. See TR-0008
security	security	all the security requirements are defined	TS-0002 clause 6.4, TR-0008	Definition of 4 protection levels suitable for different exposures. Definition of security frameworks to protect assets	TS-0003
cybersecurity	cybersecurity	all the security requirements are defined	TS-0002 clause 6.4	CPS security implies cybersecurity with additional challenges. Solutions exist to mitigate risks down to acceptable levels!	TR-0008; TS-0003
confidentiality	confidentiality	all the security requirements are defined	TS-0002 clause 6.4	Access Control and Authorization	TS-0003 clause 7
integrity	integrity	all the security requirements are defined	TS-0002 clause 6.4	implement proper protection level	TR-0008; TS-0003
availability	availability	Risks related to Denial of Service must be mitigated	TR-0008	Some mitigation mechanisms exist	TR-0008, TS-0003

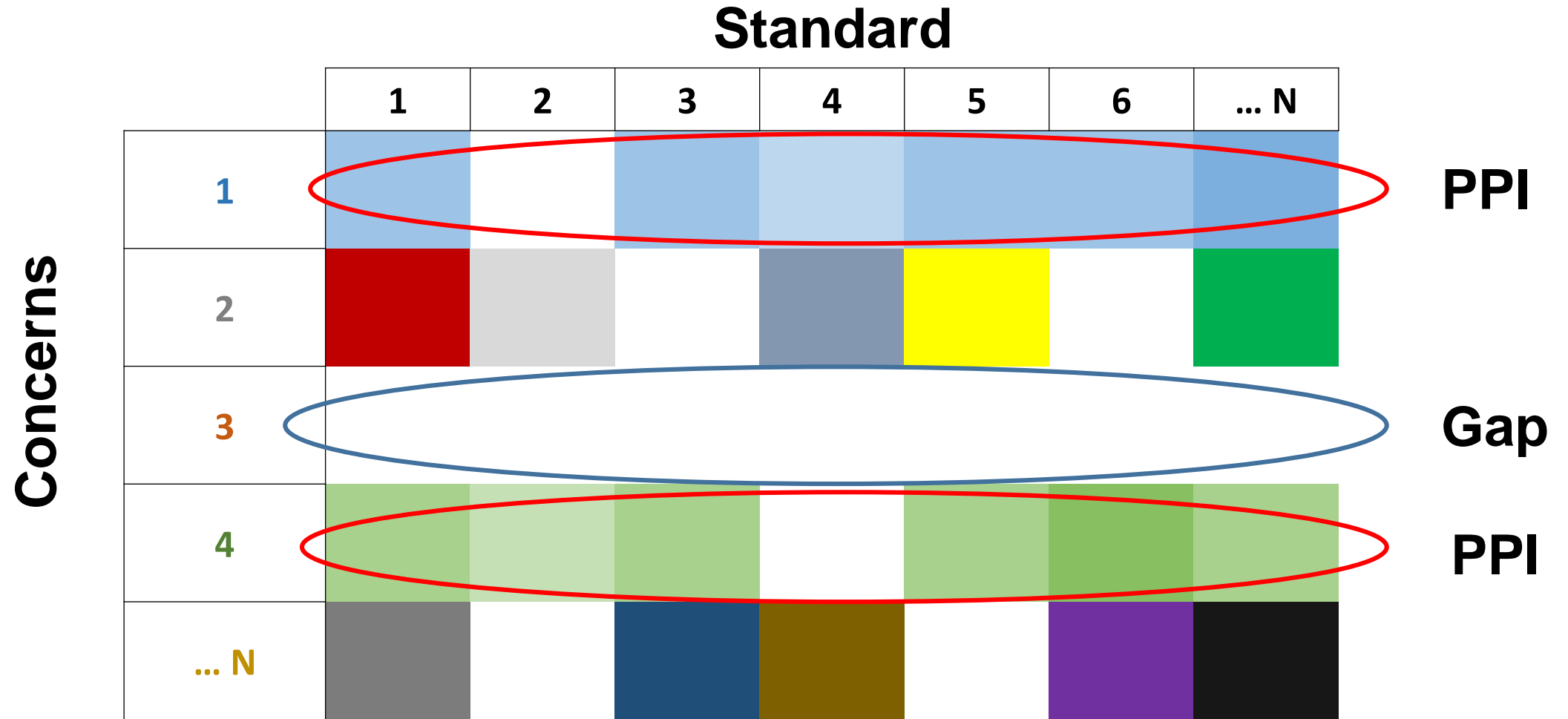
**Concern**

**Description**

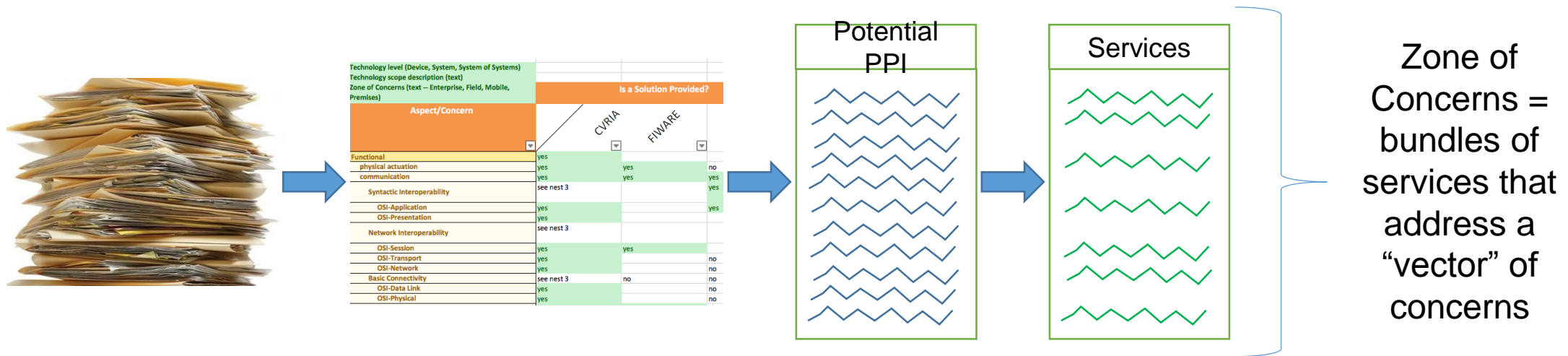
**Solution**

**Reference**

# Foundation for Cooperation

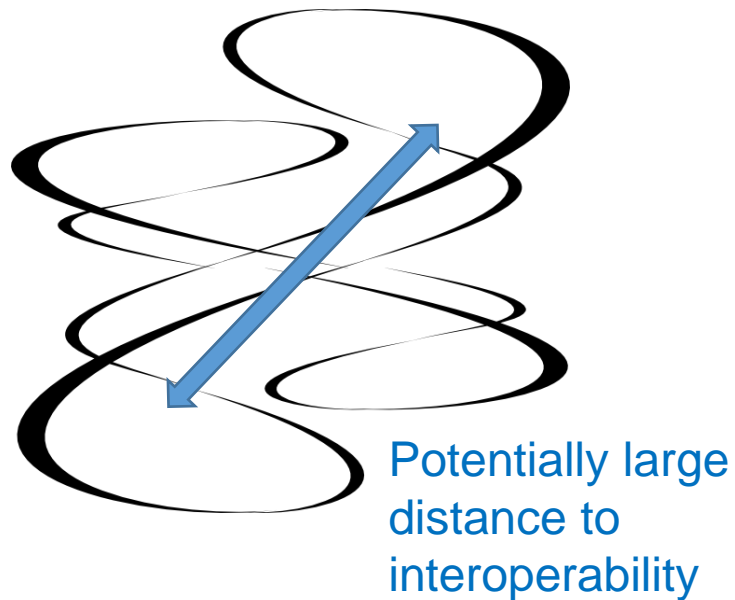


# Specs to Pivotal Points of Interoperability

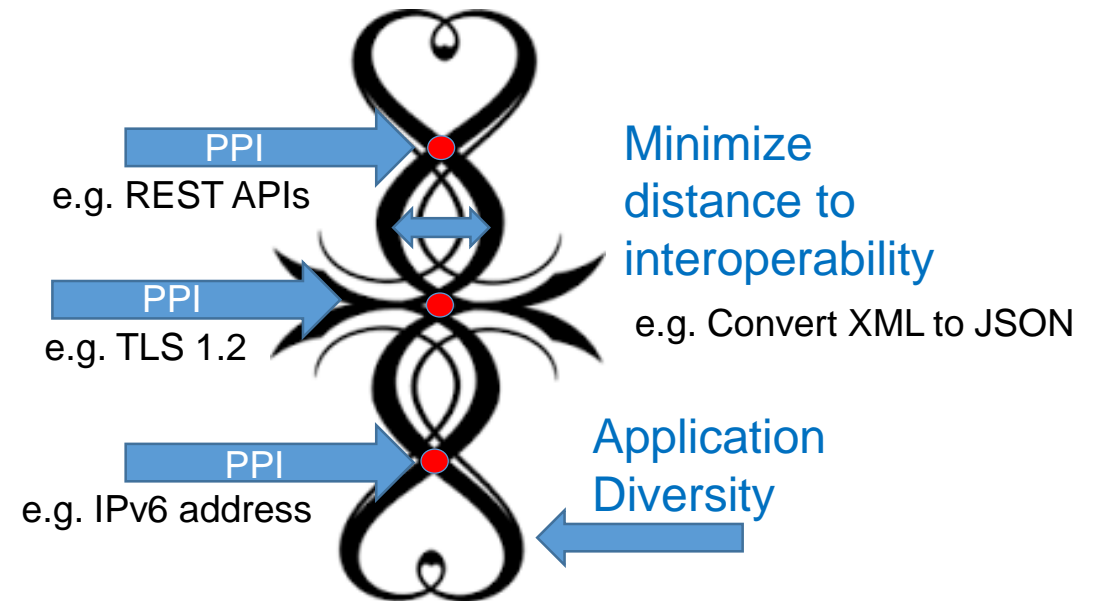


# Pivotal Points of Interoperability (PPI)

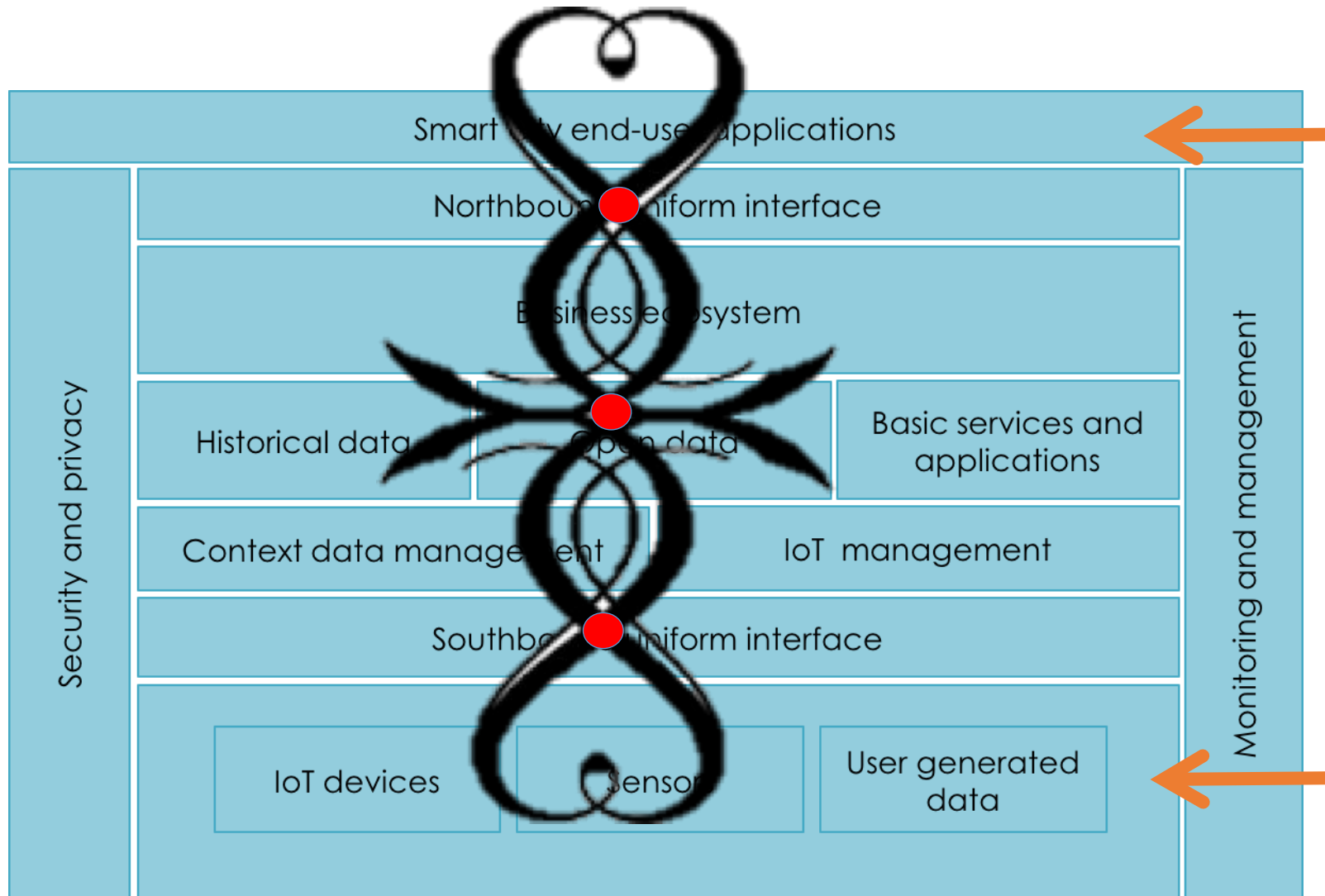
Independent  
technology  
deployments



With Pivotal  
Points of  
Interoperability

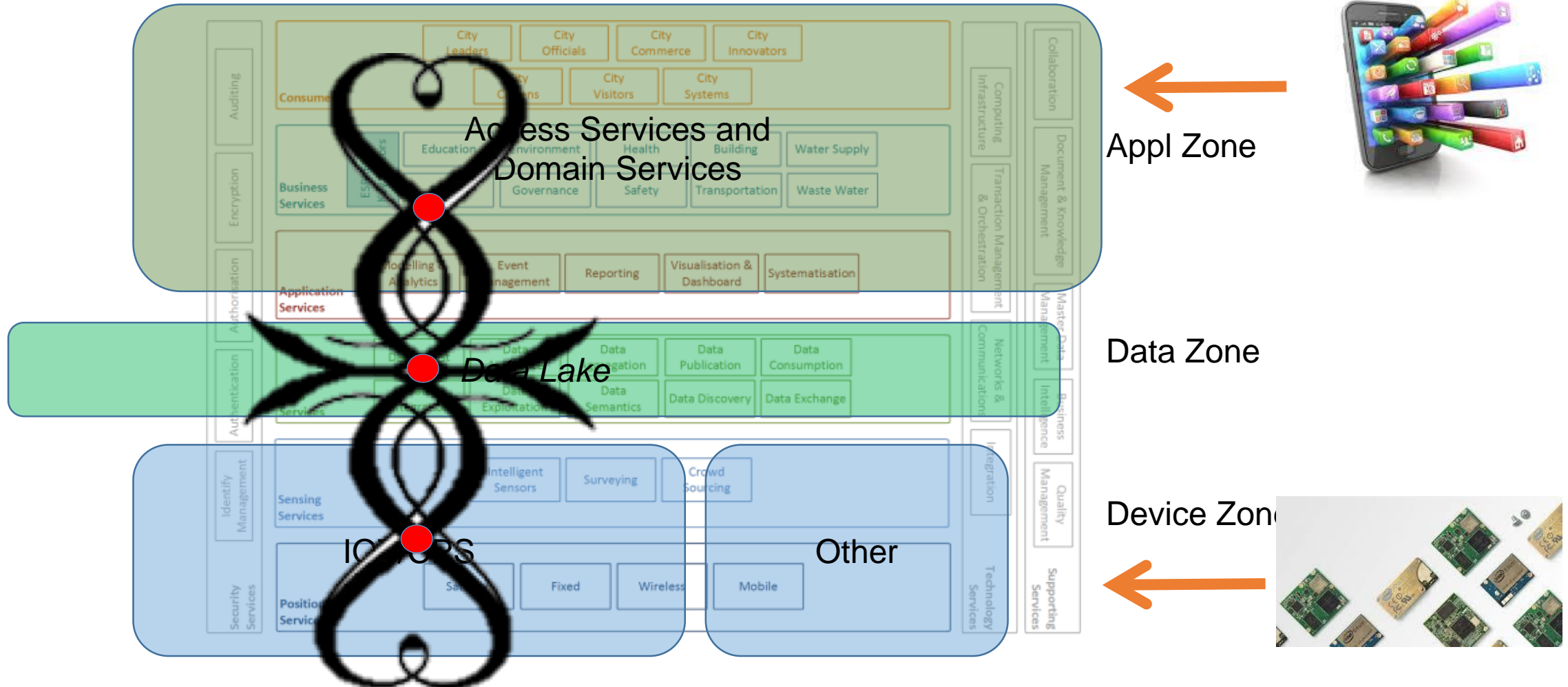


# SynchroniCity Zones of Concern





# ESPRESSO Zones of Concern





# For additional information

- Program Web Site:

**[www.nist.gov/cps](http://www.nist.gov/cps)**

- CPS Public Working Group

**[pages.nist.gov/cpspwg](http://pages.nist.gov/cpspwg)**

- Smart City Framework

**[pages.nist.gov/smartcitiesarchitecture](http://pages.nist.gov/smartcitiesarchitecture)**

- Contact:

**[chris.greer@nist.gov](mailto:chris.greer@nist.gov)**